

- (4 points) Find a polynomial $p(x)$ of degree 2 such that $p(1) = 1$, $p(2) = 6$, and $p'(2) = 6$.
- (4 points) Consider the following system:

$$\begin{cases} 2x + 3y + 4z = 3 \\ 2x + (h+1)y + 6z = 4 \\ 4x + 6y + (h-4)z = k-1 \end{cases}$$

Find all value(s) of h and k such that the system has:

- A unique solution.
- Infinitely many solutions.
- No solution.

**** Be very clear about your combinations of h and k in each case ****

- (10 points) Consider the following matrix A and its reduced row echelon form B given below.

$$A = \begin{bmatrix} 2 & 1 & -1 & 1 & 0 & 3 \\ 3 & 4 & -14 & 1 & 0 & 14 \\ 1 & -1 & 7 & 2 & 0 & -9 \\ -3 & -2 & 4 & 3 & 0 & -24 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 2 \\ 0 & 1 & -5 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & 0 & -4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Find a basis for each of the following sets.
 - $\text{Col}(A)$
 - $\text{Col}(A^T)$
 - $\text{Nul}(A)$
- Determine the dimension of $\text{Nul}(A^T)$.
- Write the fourth column of matrix A as a linear combination of the other columns of A .
- Determine a vector that is in $\text{Nul}(A)$ whose first and second entries are 18 and -5 , respectively.

- Given that $\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{bmatrix}$ is a particular solution to $A\mathbf{x} = \mathbf{b}$, determine the general solution to $A\mathbf{x} = \mathbf{b}$.

- (3 points) Let $A = \begin{bmatrix} k & 1 & 2 \\ 1 & k & 1 \\ 1 & 1 & 1 \end{bmatrix}$.

- Find $\det(A)$ in terms of k .
- Find all values for k such that A is non-invertible.

- (6 points) Let S and T both be linear transformations from \mathbb{R}^2 to \mathbb{R}^2 . Let S be the transformation that reflects vectors through the x -axis. Let T be a *horizontal shear* such that $T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$.

- Find the standard matrix A of transformation S .
- Find the standard matrix B of transformation T .
- Find the standard matrix C of transformation $S \circ T$.
- Find a non-zero vector $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ such that $S(\mathbf{v}) = T(\mathbf{v})$.

- (5 points) Let $A = \begin{bmatrix} 2 & 4 \\ 2 & 6 \\ -1 & 6 \\ 0 & -6 \end{bmatrix}$ and $\mathbf{b} = \begin{bmatrix} -6 \\ -14 \\ -29 \\ 24 \end{bmatrix}$.

- Determine an LU -factorization for matrix A .
- Use your answer in part (a) to solve the equation $A\mathbf{x} = \mathbf{b}$.

7. (3 points) Express the matrix $\begin{bmatrix} 2 & 4 \\ 2 & 3 \end{bmatrix}$ as a product of elementary matrices.
8. (3 points) Given $A = \begin{bmatrix} -2 & 6 \\ 4 & -7 \end{bmatrix}$, find a matrix X such that $XA - XA^T = A$.
9. (4 points) Let A and B be 4×4 matrices where $\det(A)$ is unknown and $\det(B) = -2$.
- If $A^T A = 2I$. What are the possible values of $\det(A)$?
 - Find $\det((B^{-1})^3 \text{adj } B)$.
10. (3 points) Let A be a 3×3 matrix such that $A \begin{bmatrix} 4 \\ 6 \\ 9 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}$, $A \begin{bmatrix} 6 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ -2 \\ 0 \end{bmatrix}$, and $A \begin{bmatrix} 4 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.
- Find a vector \mathbf{u} such that $A\mathbf{u} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$.
 - Determine A^{-1} .
11. (2 points) Matrix A is called “skew-symmetric” if $A^T = -A$. Given that $n \times n$ matrices A and B are skew-symmetric and $AB = -BA$, show that matrix AB must also be skew-symmetric.
12. (3 points) Consider a single matrix A with all the following properties:
- A is in RREF.
 - The first two columns of A form a linearly independent set.
 - The null space of A is in \mathbb{R}^5 .
 - The span of the fourth column of A is a point in \mathbb{R}^3 .
 - The dimension of the null space of A is greater than the rank of A .
- What size matrix must A be?
 - Give an example of a matrix that satisfies all the conditions above.
13. (3 points) Let $\begin{bmatrix} W & O \\ X & Y \\ Z & I \end{bmatrix} \begin{bmatrix} A & O \\ B & I \end{bmatrix} = \begin{bmatrix} I & O \\ O & A \\ O & I \end{bmatrix}$. Given that A is a square matrix, express the block entries W, X, Y , and Z in terms of A and B .
- Justify each step.
14. (7 points) Let $T: \mathbb{P}_2 \rightarrow \mathbb{R}^2$ be the linear transformation defined by $T(p(x)) = \begin{bmatrix} p(1) \\ p'(0) \end{bmatrix}$.
- Find the image of $q(x) = x + x^2$ under transformation T .
 - Find a polynomial $r(x)$ such that $T(r(x)) = \begin{bmatrix} 5 \\ 2 \end{bmatrix}$.
 - Find a basis for the kernel of T .
 - Is T a one-to-one transformation? Justify.
15. (6 marks) Let $\mathcal{H} = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x(2y - 3z) = 0 \right\}$.
- Is \mathcal{H} closed under vector addition? Justify.
 - Is \mathcal{H} closed under scalar multiplication? Justify.
 - Is \mathcal{H} a subspace of \mathbb{R}^3 ?
16. (3 points) Let $\mathcal{H} = \left\{ \mathbf{x} \in \mathbb{R}^4 : \mathbf{x} \cdot \begin{bmatrix} 1 \\ -3 \\ 0 \\ 2 \end{bmatrix} = 0 \right\}$. Given that \mathcal{H} is a subspace of \mathbb{R}^4 , find a basis for \mathcal{H} .
17. (3 points) Let $p(x) = 2 + 3x - x^2$, $q(x) = -3 - 5x + 3x^2$, and $r(x) = 4 + 3x + 7x^2$. Show that $r(x) \in \text{Span}\{p(x), q(x)\}$.
18. (8 points) Given the planes $\mathcal{P}_1: 2x - y + 5z = 8$ and $\mathcal{P}_2: x - y + 2z = 4$, and given the point $A(5, -3, 2)$.
- Find the cosine of the angle between the planes \mathcal{P}_1 and \mathcal{P}_2 .
 - Find the point on the plane \mathcal{P}_1 closest to A .

- (c) Find an equation for the line containing point A that is parallel to both \mathcal{P}_1 and \mathcal{P}_2 .
19. (5 points) Given the line $\mathcal{L}: \mathbf{x} = \begin{bmatrix} k \\ 2 \\ 0 \end{bmatrix} + t \begin{bmatrix} h \\ 1 \\ -2 \end{bmatrix}$ and the plane $\mathcal{P}: x - 2y + 4z = 0$, find conditions on h and k for each of the following cases.
- ** Be very clear about your combinations of h and k in each case ****
- (a) \mathcal{L} and \mathcal{P} are parallel and do not intersect.
 (b) \mathcal{L} is contained within plane \mathcal{P} .
 (c) \mathcal{L} and \mathcal{P} intersect at a point.
20. (9 points) Given the points $P(0, 0, -2)$, $Q(2, 3, 4)$, $R(4, 6, 5)$, and $S(6, 11, 10)$, find the following:
- (a) The area of triangle PQR .
 (b) An equation of the form $ax + by + cz = d$ for the plane containing points P, Q , and R .
 (c) The volume of the parallelepiped with edges \overrightarrow{PQ} , \overrightarrow{PR} , and \overrightarrow{PS} .
 (d) A point on the line through P and Q which is two units away from P .
21. (2 points) Show that if $\text{Proj}_{\mathbf{v}}\mathbf{u} = \text{Proj}_{\mathbf{v}}\mathbf{w}$, then $\mathbf{u} - \mathbf{w}$ is orthogonal to \mathbf{v} .
22. (4 points) Complete the following sentences with the word *must*, *might* or, *cannot*, as appropriate.
- (a) If \mathbf{u} is in $\text{Span}\{\mathbf{v}\}$, then \mathbf{v} _____ be in $\text{Span}\{\mathbf{u}\}$.
 (b) If A is invertible, then $\text{Row}(A)$ _____ be identical to $\text{Col}(A)$.
 (c) If the 3×3 coefficient matrix A of the system of linear equations $A\mathbf{x} = \mathbf{b}$ has rank 2, then the system _____ be inconsistent when $\mathbf{b} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$.
 (d) If A, B , and C are square matrices such that $ABC^2 = I$ then matrix C _____ be invertible.

ANSWERS

1. $p(x) = -2 + 2x + x^2$
2. (a) $h \neq 2$ or $12, k \in \mathbb{R}$ (b) $h = 12$ and $k = 7$ OR $h = 2$ and $k = 2$ (c) $h = 12$ and $k \neq 7$ OR $h = 2$ and $k \neq 2$
3. (a) (i) $\left\{ \begin{bmatrix} 2 \\ 3 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \\ -1 \\ -2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} \right\}$ (ii) $\left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \\ 0 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -5 \\ 0 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ -4 \end{bmatrix} \right\}$ (iii) $\left\{ \begin{bmatrix} -2 \\ 5 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ -3 \\ 0 \\ 4 \\ 0 \\ 1 \end{bmatrix} \right\}$ (b) 1
- (c) $\begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 \\ 3 \\ 1 \\ -3 \end{bmatrix} + \frac{3}{4} \begin{bmatrix} 1 \\ 4 \\ -1 \\ -2 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 3 \\ 14 \\ -9 \\ -24 \end{bmatrix}$ (d) $\begin{bmatrix} 18 \\ -5 \\ -4 \\ -20 \\ 0 \\ -5 \end{bmatrix}$ (e) $\begin{cases} x_1 = 1 - 2r - 2t \\ x_2 = 2 + 5r - 3t \\ x_3 = 3 + r \\ x_4 = 4 + 4t \\ x_5 = 5 + s \\ x_6 = 6 + t \end{cases}$
4. (a) $\det(A) = k^2 - 3k + 2$ (b) $k = 1$ or 2
5. (a) $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ (b) $B = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ (c) $C = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & -1 \end{bmatrix}$ (d) $\mathbf{v} = \begin{bmatrix} k \\ 0 \end{bmatrix}; k \in \mathbb{R}$
6. (a) $LU = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ -1/2 & 4 & 1 & 0 \\ 0 & -3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 \\ 0 & 2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$ (b) $L\mathbf{y} = \mathbf{b} \rightarrow \mathbf{y} = \begin{bmatrix} -6 \\ -8 \\ 0 \\ 0 \end{bmatrix}; U\mathbf{x} = \mathbf{y} \rightarrow \mathbf{x} = \begin{bmatrix} 5 \\ -4 \end{bmatrix}$
7. $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -4 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ (many answers)
8. $X = A(A - A^T)^{-1} = \begin{bmatrix} 3 & 1 \\ -7/2 & -2 \end{bmatrix}$
9. (a) $\det(A) = \pm 4$ (b) 1

10. (a) $\mathbf{u} = \begin{bmatrix} -3 \\ 0 \\ -1 \end{bmatrix}$ (b) $A^{-1} = \begin{bmatrix} 4/3 & -3 & 4 \\ 2 & 0 & 3 \\ 3 & -1 & 1 \end{bmatrix}$
11. $(AB)^T = (-BA)^T = -A^T B^T = -(-A)(-B) = -(AB)$
12. (a) 3×5 (b) $A = \begin{bmatrix} 1 & 0 & a & 0 & c \\ 0 & 1 & b & 0 & d \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$; $a, b, c, d \in \mathbb{R}$
13. $W = A^{-1}$, $X = -ABA^{-1}$, $Y = A$, $Z = -BA^{-1}$
14. (a) $T(q(x)) = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ (b) $r(x) = a + 2x + cx^2$; where $a + c = 3$ (c) $\{1 - x^2\}$ (d) No. Many counter-examples possible.
15. (a) No. Many counter-examples possible. (b) Yes. Given $\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \in \mathcal{H}$, show $k\mathbf{u} = \begin{bmatrix} ku_1 \\ ku_2 \\ ku_3 \end{bmatrix} \in \mathcal{H}$ for all k . (c) No, not closed under addition.
16. $\left\{ \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$
17. $r(x) = 11p(x) + 6q(x)$
18. (a) $\cos \theta = \frac{13}{6\sqrt{5}}$ (b) $(4, -5/2, -1/2)$ (c) $\mathbf{x} = \begin{bmatrix} 5 \\ -3 \\ 2 \end{bmatrix} + t \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$
19. (a) $h = 10$ and $k \neq 4$ (b) $h = 10$ and $k = 4$ (c) $h \neq 10$ and $k \in \mathbb{R}$
20. (a) $\frac{1}{2}\sqrt{325}$ (b) $15x - 10y = 0$ (c) 20 units³ (d) $(4/7, 6/7, -2/7)$ or $(-4/7, -6/7, -26/7)$
21. $\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{\mathbf{w} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} \rightarrow \mathbf{u} \cdot \mathbf{v} = \mathbf{w} \cdot \mathbf{v} \rightarrow \mathbf{u} \cdot \mathbf{v} - \mathbf{w} \cdot \mathbf{v} = 0 \rightarrow (\mathbf{u} - \mathbf{w}) \cdot \mathbf{v} = 0$
22. (a) might (not if \mathbf{u} is the zero vector) (b) must (both equal all \mathbb{R}^n) (c) might (as that column changes during row-reduction)
(d) must (and $C^{-1} = ABC$)