

THEORY

1.

$$A \sim B \Rightarrow B \sim A$$

$$A \sim B \Rightarrow \exists \underbrace{E_1 E_2 \dots E_n}_{\text{elementary matrices}} \text{ such that } E_n \dots E_2 E_1 A = B \Rightarrow A = (E_n \dots E_2 E_1)^{-1} B = E_1^{-1} E_2^{-1} \dots E_n^{-1} B$$

when E_i^{-1} is an elementary matrix (for all i) (inverse of an elementary is elementary) $\Rightarrow B \sim A$

2.

$$A \sim B, B \sim C \Rightarrow A \sim C$$

$$A \sim B \Rightarrow \exists \underbrace{E_1 E_2 \dots E_n}_{\text{elementary matrices}} \text{ such that } E_n \dots E_2 E_1 A = B \Rightarrow A = (E_n \dots E_2 E_1)^{-1} B = E_1^{-1} E_2^{-1} \dots E_n^{-1} B$$

$$B \sim C \Rightarrow \exists \underbrace{F_1 F_2 \dots F_k}_{\text{elementary matrices}} \text{ such that } F_k \dots F_2 F_1 B = C$$

$$\text{such that } \underbrace{F_k \dots F_2 F_1}_{\text{all elementary matrices except } A} \underbrace{E_n \dots E_2 E_1 A}_{\text{substituting for } B} = C \Rightarrow A \sim C$$

Equivalences Let A be an $n \times n$ square matrix and $R = \text{RREF of } A$.

(1) $A^{-1} \exists$ (2) $A\vec{x} = \vec{b}$ has a unique solution

(3) $A\vec{x} = \vec{0}$ has a unique solution (4) $\text{Rank } A = \# \text{ leading ones in } R = n$

(5) $A \sim I$ (6) $A =$ a product of elementary matrices (7) $\det A \neq 0$

"Alternate" list of Equivalent Statements

(1) $A^{-1} \nexists$ (2) $A\vec{x} = \vec{b}$ has a parametric solution or is inconsistent

(3) $A\vec{x} = \vec{0}$ has a parametric solution (hence, nontrivial solutions) (4) $\text{Rank } A < n$

(5) $A \sim R$ (where R has at least one row of zeros)

(6) A cannot be written as a product of elementary matrices (7) $\det A = 0$

Problems - Anton: Ex 2.1 9, 12, 13, 18, 19

Ex 2.2 2, 3, 4, 7, 10, 12, 13, 17

Ex 2.3 2, 3, 4, 5, 6-12, 13

Ex 2.4 1, 2, 4, 5, 7, 9, 10, 11, 12, 22, 16-18, 23, 25, 26
Cramer's Rule! theory

Ex 1.6 ; 24, 25 (theory) , Ex 1.5 ; 19, 20 (theory)

Note in (20) A is singular means A is square and $A^{-1} \nexists$

(1) If \vec{x}_1 is a solution to $A\vec{x} = \vec{b}$ and \vec{x}_2 is a solution to $A\vec{x} = \vec{0}$, show that $\vec{x}_1 + k\vec{x}_2$ is a solution to $A\vec{x} = \vec{b}$.

(2) Let A, B, P represent $n \times n$ invertible matrices (i.e. $A^{-1}, B^{-1}, P^{-1} \exists$) and $B = PAP^{-1}$

(a) show that $B^2 = PA^2P^{-1}$ (b) show that $B^{-1} = PA^{-1}P^{-1}$

(3) (a) If $A^2 = I$, prove $\det A = \pm 1$ (b) If $A^2 = A$, prove $\det A = 0$ or 1 } (Take the det of both sides)

(4) $A_{3 \times 3}$; $B_{3 \times 3}$ such that $\det(3A^{-1}) = -5$ and $\det(A^2B^{-1}) = -5$. Find $\det A$; $\det B$.

(Answer: $\det A = -\frac{27}{5}$; $\det B = -\frac{(27)^2}{125}$)